

Engineer Application Note EE-101

DSP processor control protocol

Rev 4 Updated on 2022-3-28

introduction

External control programming supports UDP,RS232 and RS232 coding, and the control protocol covers all control parameters of the processor, including parameter control, parameter acquisition, and preset call.

When using UDP control, the default port is 50000, and the port can be set in "Device Settings" through the DSP Controller software.

Using RS232/RS485 control, the default baud rate is 115200, data bit 8, stop bit 1, no check digit. It can also be set in "Device Settings". When **RS232/RS485 is sent, the interval between messages needs to be maintained at more than 200 milliseconds.**

If the central control needs to reply, please turn on the central control reply switch in the "Device Settings" in the DSP Controller software.

There are two versions of the control protocol, V1 and V2, V1 is a fixed-length message packet, and V2 is a variable-length message packet.

Note: This document is only applicable to the DSP fixed architecture and is not compatible with the company's open software architecture products. This documentation is updated with product updates, please pay attention to the purchased products and contact after-sales for the latest documents.

V1 versioning protocol

Software encoding rules (12 bytes total).

byte1	byte2	byte3	byte4	byte5~12
0xb3	Message type	0x00	0x00	data

The byte3 byte may not be 0x00 when the PC software takes the value, because the PC software has not been updated to the latest control protocol. However, it does not affect the use, and the byte3 field is a reserved field in the V1 version.

byte4 is also used as an identifier for the return code to identify that the command is a reply command. V1 sends a control command of 0x00 and the device replies with 0xe0.

Message type (byte2): 0x21 (parameter control), 0x22 (parameter acquisition), 0x13 (switching scene).

When the message types are 0 **x21 and 0x22**, the data area format is:

byte5-6	Module ID, see Appendix A
byte7-8	See Appendix B for parameter types

byte9-10	Parameter value 1
byte11-12	Parameter value 2

Most modules only have one valid parameter, such as controlling the compressor switch, switch value (1-off, 0-on), and only need to fill in parameter value 1.

In the case of two parameters, there are input module, output module, equalization module, and automix module.

Input and output module, parameter value 1 fill in the channel number (starting from 0), parameter value 2 fill in the parameter value, such as mute (1-mute,0 - Non-mute).

The control input block channel one gain step is +2dB: B32100002B010A000000C800

Control input module channel one gain to -36dB: B32100002B0101000000F0F1

Equalization module, parameter value 1 fills in the segment number (starting from 0), parameter value 2 fills in gain, Q value, frequency, etc.

Automix module, subchannel setting uses 2 parameters, parameter 1 fill in the channel number, parameter 2 fill in the specific value, such as priority, gain, mute, etc.

The frequency of the control input channel one equalizer subsegment 3 is 450Hz:

B3210000610003000200C201

Control automix subchannel 5 mute switch: B3210000A100060004000100

Matrix routing has three parameters, the first is the input channel number, the second is the output channel number, and the third is the routing switch. At this time, the byte9 of parameter value 1 is filled in with the channel number, byte10 is filled in with the output channel number, and the parameter value 2 is filled in with the routing switch.

The switch to control the mixing module input 3 to output 4 is on: B3210000A600010002030100

There are three parameters to get a matrix route, the first is the input channel number, the second is the output channel number, and the third is the routing switch. At this time, the byte9 of parameter value 1 enters the channel number, byte10 fills in the output channel number, and the parameter value 2 fills in the routing switch.

The control mix module input 3 to output 4 switch on:

Send: B3220000A600010002030000

Remark:

22: obtain

0203: Represents input and output (starting from 00).

0000: The default is OK

Re: B32200E0A600010002030100

Remark:

0203: Represents input and output (starting from 00).

0000:0000 for off, 0100 for on

When the message type is 0x13 switching scenes (preset), bYTE5-6 fill in the scene number, a total of 16 sets of scenes (0-15) .

Switch preset 10: B31300009000000000000000

For floating-point type values, multiply by 100 to become a 16-bit integer before

transmission, such as 12.15, send 1215, hexadecimal 0x04BF. -4.9, send -490, hexadecimal is 0xFE16.

Assuming a value of 3 needs to be set:

We need to convert the value X100 to hexadecimal to 12C. Only when the high bit changes to 2C 01 before sending this instruction will our processor recognize the value as set to 3

V2 versioning protocol

Software coding rules (variable length)

byte1	byte2	byte3	byte4	byte5~132
0xb3	Message type	length	0x01	data

byte4 is also used as an identifier for the return code to identify that the command is a reply command. V2 sends the control command as 0x01 and the device replies with 0xe1

There are several types of message types as shown in the following table.

Message type	length	data format	illustrate
0x21 (parameter control).	Variable length	byte5	0x1 - Output 0x2 - Input 0x3 - Reserved 0x4 - Feedback suppression 0x5 - Automatic gain 0x6 - Voice tracking
byte6 The starting channel number (starting at 0). byte7 End channel number (starting at 0). byte8 Parameter types (as defined in Appendix B). byte9-72 Parameter values, each channel occupies two bytes, sorted sequentially. It can store up to 32 channels. If the parameter values of each channel are the same, fill in one.			
The control input 2-6 channels are muted, the code is: b3210a010201050201000100010001000100			
0x22 (parameter acquisition).	Variable length	byte5	0x1 - Output 0x2 - Input 0x3 - Reserved 0x4 - Feedback suppression 0x5 - Automatic gain 0x6 - Voice tracking
byte6 The starting channel number (starting at 0). byte7 End channel number (starting at 0). byte8 Parameter types (as defined in Appendix B). byte9-72 Parameter values, each channel occupies two bytes, sorted sequentially. It can store up to 32 channels.			
Get the input 2-6 channel level with the code: b3220a010201050c000000000000000000000000000000			
The reply was: B3220A010201050C40ED5AF179EC96ECEEEC			
0x74 (externally controlled).	Variable length	byte5	Control Type: 0x1 - GPIO control 0x2 – RS232 sends the code 0x3 – RS485 sends the code 0x4 – Turn on central control reply 0x5 – Gets the number of device channels

			0x6 – Resets the current preset, does not save 0x7 – Set the RS485 direction 0x8 – UDP forwarding code 0x9 – Turn on the System Debug switch
	byte6		Data length (valid data length populated with byte9-132).
	Byte7-8		0x0000
	byte9-132		Depending on the byte5 control type, see the external control description.

External control description

preset, does not save).	b374040106000000	
Control type	data format	illustrate
0x7 (sets RS485 direction).	byte9-12	Direction: 1 - input, 0 - output
	RS485 defaults to input mode, set the output format as follows: b3740801070000000000000000	
0x8 (UDP forwarding code).	byte 9-12	IP address
	byte 13-14	port
	byte 15-16	Forward data length
	byte 17-132	Forward data
	Forward the string "Hello, DSP." to 192.168.1.165 on device port 3001: b374180108000000c0a801a5b90b0c0048656c6c6fa3ac4453502e00	
0x9 (system debug switch).	byte 9-12	1 - Turn debugging on, 0 - Turn off debugging
	Turn on the debug switch: b37408010900000001000000 This function is only for debugging, and the system will output runtime logs to the serial port.	

Appendix A Module ID Assignment

Module name	ID	Module name	ID
Input source	299	Output channel 1-32 high and low pass	167~198
Input channel 1-32 expander	1~32	Output channel 1-32 equalizer	199~230
Input channel 1-32 compressor	33~64	Output channel 1-32 delay	231~262
Input channels 1-32 automatic gain	65~95	Output channel 1-32 limiter	263~294
Input channel 1-32 equalizer	97~128		
Input channels 1-32 feedback rejection	129~160		
Automix	161	Echo cancellation selector	162
Echo cancellation	163	Noise suppression selector	164
Noise suppression	165		
Audio mixer	166		
output	295		
System control	296		

Appendix B Module Parameter Types

Module name	The parameter type	illustrate	Module name	The parameter type	illustrate
Input source	0x1	gain	output	0x1	gain
	0x2	mute		0x2	mute
	0x3	sensitivity		0x3	Channel name
	0x4	Phantom power switch		0x4	Inverted
	0x5	Signal generator type		0x5	sensitivity
	0x6	Signal generator frequency		0x6	Gain step
	0x7	The magnitude of the sine wave gain		0x7	Link
	0x8	Channel name		0x8	Channel level
	0x9	Inverted			
	0xa	Gain step			
Delay	0xb	Link	Extender		
	0xc	Channel level		0x1	switch
equalizer	0x1	Bypass switch		0x2	threshold
	0x2	millisecond		0x3	ratio
	0x3	microsecond		0x4	Settling time
Feedback suppression	0x1	Equalizer master switch	Compressor	0x5	Release time
	0x2	Subsegment switch		0x1	Compressor switch
	0x3	frequency		0x2	Compressor threshold
	0x4	gain		0x3	Compressor ratio
	0x5	Q value		0x4	Settling time
	0x6	type		0x5	Recovery time
Voice tracking	0x1	Tracking thresholds	Automatic gain	0x6	Gain compensation
	0x3	Reaction time		0x1	Bypass switch (0 on/1 off).
	0x5	Wheel clearance		0x2	threshold
	0x7	Enable tracing		0x3	Target threshold
	0x9	Serial port type		0x4	ratio
	0xb	agreement		0x5	Settling time
	0xd	Enable the microphone settings	0xand	0x6	Release time
	0xf	The command string		0x8	Default microphone
	0x11	Command enables		0xa	Toggle the default microphone time
				0xc	Number of rounds
				0x10	Mike Priority
				0x12	Camera address
					Preset points
					The command type
					Send
					Save

Document history

recension	description
<i>Rev 1 – 2018-8-10</i>	Initial version release
<i>Rev 2 – 2018-8-17</i>	V1 Release Notes Modified
<i>Rev 3 – 2019-7-23</i>	Added return code recognition, fixed V2 forwarding code
<i>Rev 4 – 2022-3-28</i>	Added feedback suppression and automatic gain parameter control code, and added voice tracking reference control code